



# **Zephyr in Practice: From Functional Design to Efficient Implementation**

**Zephyr Meetup Garching - November 20th 2025**

**Tobias Kästner, inovex**



# That's me



Tobias Kaestner



@tobiaskaestner



@tobiaskaestner

Solution Architect Medical IoT @ inovex GmbH

#FOSS4MEDICAL

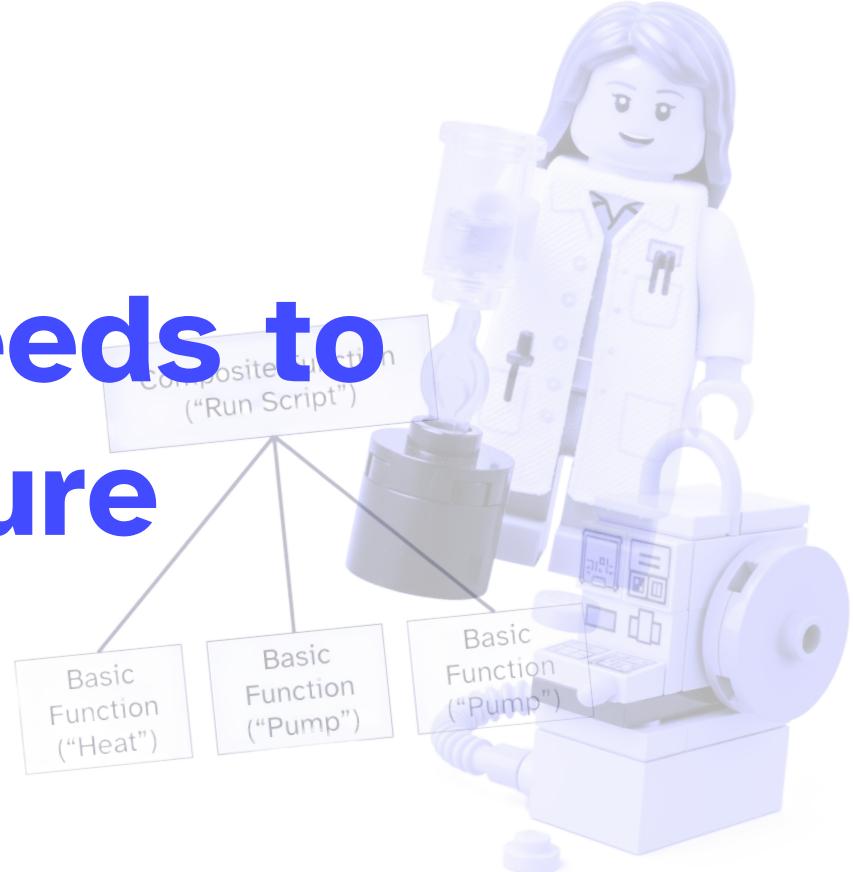
- PhD in Physics (long ago)
- SW/System Architect since 15 years
  - mainly Medical Devices
- Trainer & Technical Consultant
  - SW-Architecture, Zephyr, Yocto
- In Love w/ Zephyr since 2016
  - realised several prototype projects for life-science R&D
  - Maintainer of TiacSys-Bridle Project
  - Participant Zephyr Safety-WG

# Agenda

- From User Needs to SW Architecture
- Architecting Embedded SW with Zephyr
- Designing Embedded SW with Zephyr



# From User Needs to SW Architecture



# A day in the lab - The life-science domain



- Developing new diagnostic tests requires extensive research & development
  - to find correct chemical formulation
  - to determine physical parameters
  - to develop algorithms for signal extraction
- Scientists can be supported by devices to automate many/all of the required tasks

# Modelling the Life-Science Domain



## Doing lab experiments requires

- moving & mixing liquids
- heating & cooling reagents
- measuring signals from chemical reactions
- running prescribed protocols (assays) repeatedly

## System functionalities

- pump
- heat, cool
- measure signals (electrodes, image)
- run a script



# System functionalities & modalities

**System functions** expressed in terms of **the specific domain**

**Modalities** describe recurring **facets** or **aspects** of system functions



## System functionalities

- pump
- heat, cool
- measure signals (electrodes, image)
- run a script

## Cross-cutting modalities

How to

- invoke
- compose
- monitor/observe
- parametrize

the system functions

# System functionalities & modalities

**System functions** expressed in terms of **the specific domain**

**Modalities** describe recurring **facets** or **aspects** of any system function



## System functionalities

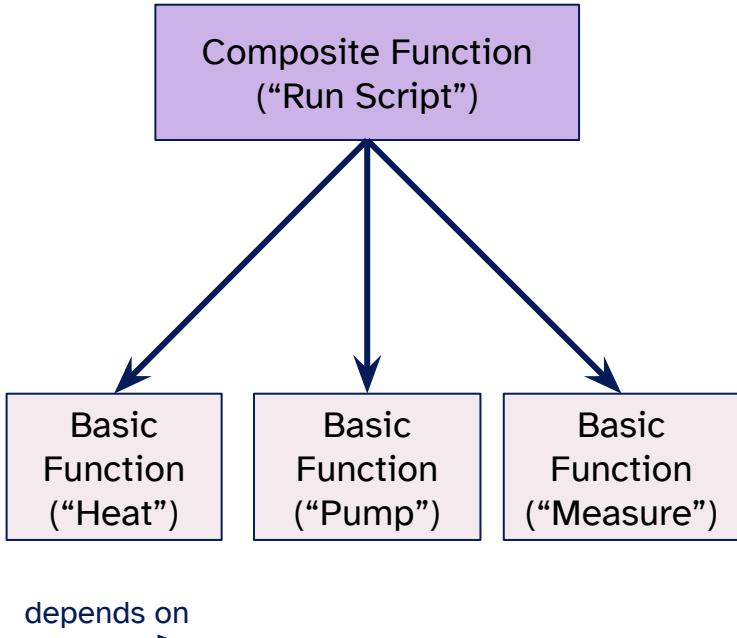
- application domain specific
- require most likely specific technical realization

## Cross-cutting modalities

- generic to most/all computerized systems
- can most likely re-use existing technical realizations

**Caution:** In the real world most things fall onto a spectrum, eg. “run script”

# System function composability

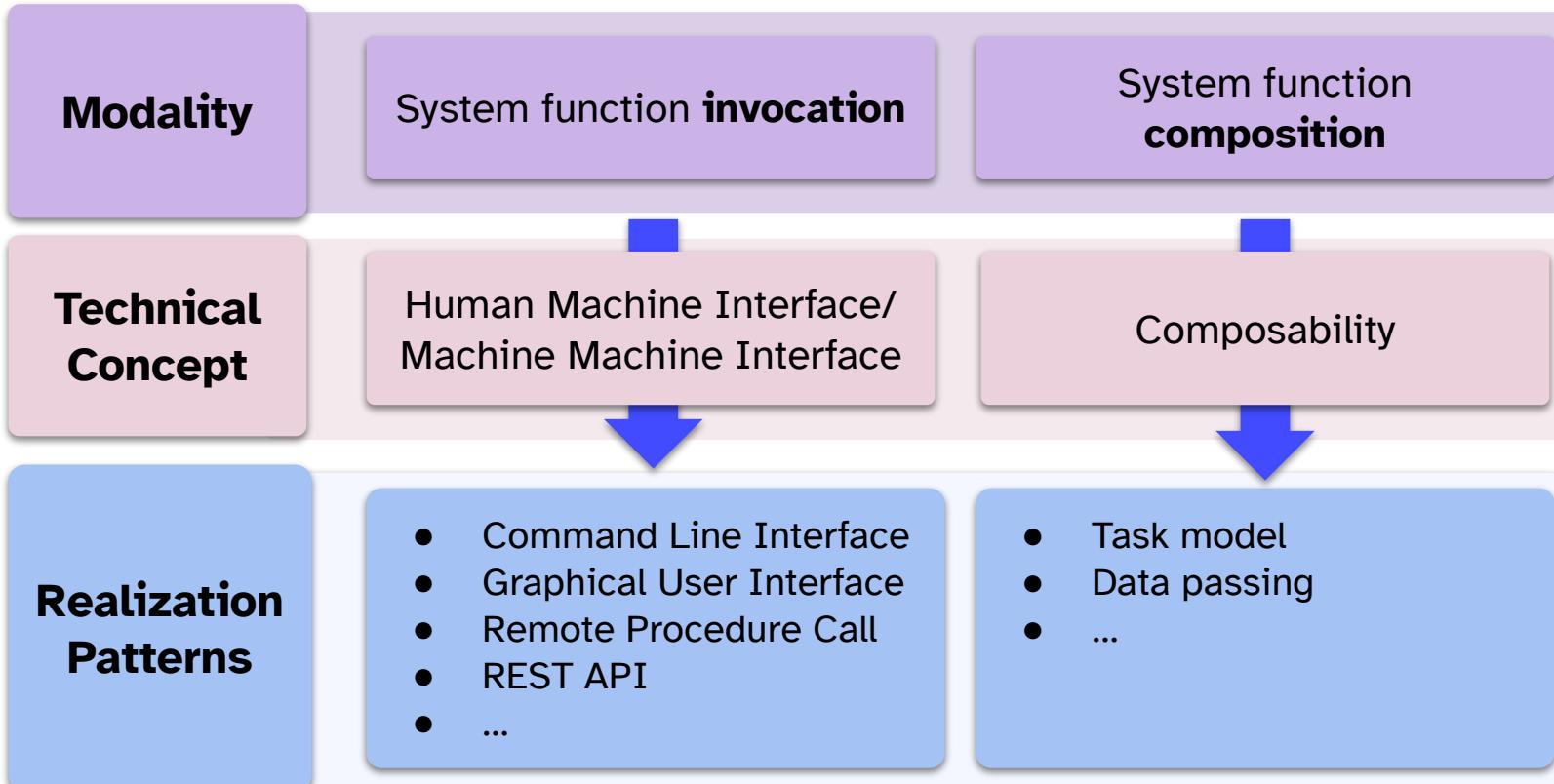


**User-level tasks** are typically expressed as **composite system functions**

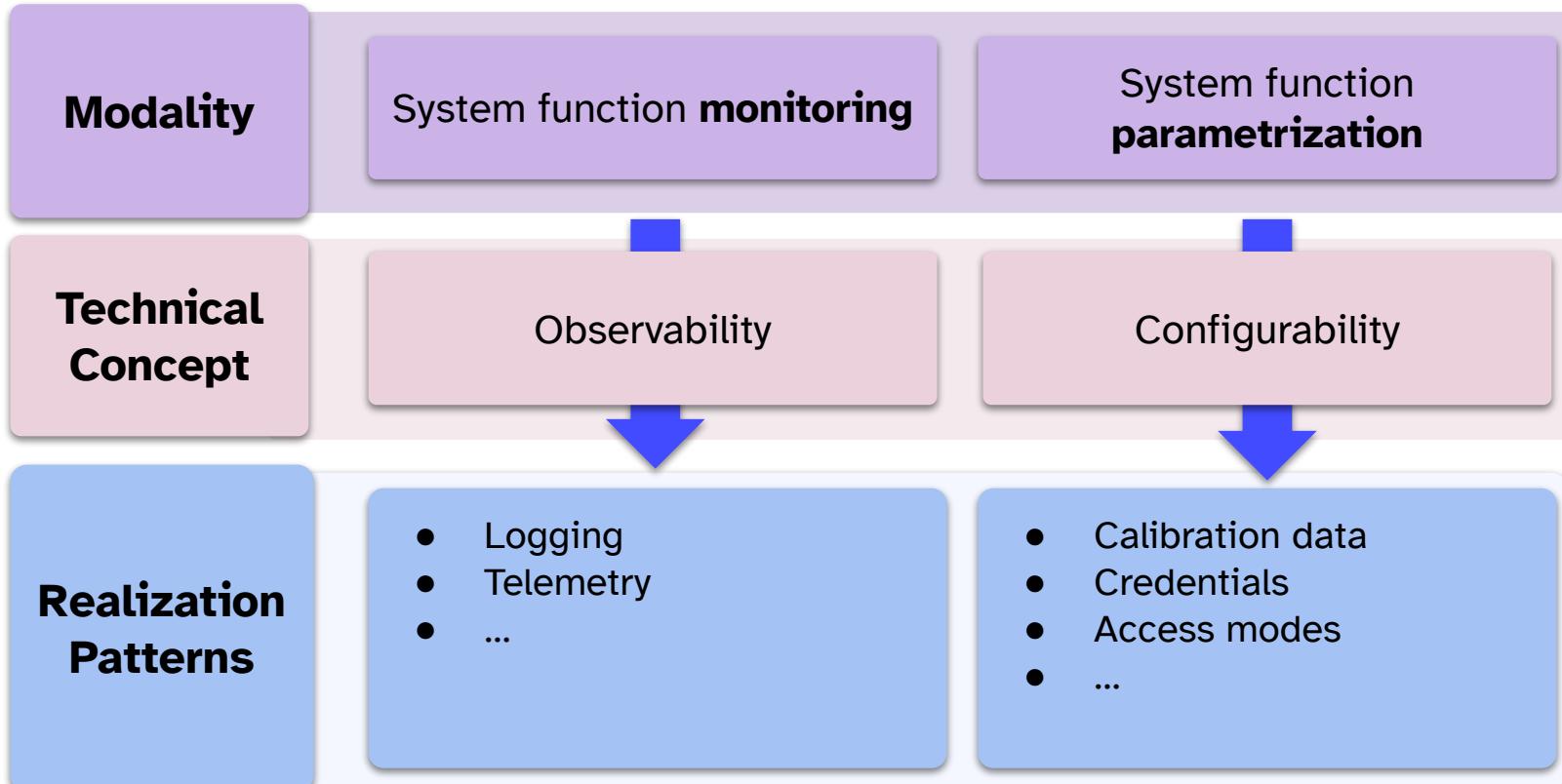
Decompose system functions to

- model functional dependencies
- identify **mutually independent** basic functions

# Cross-cutting modalities



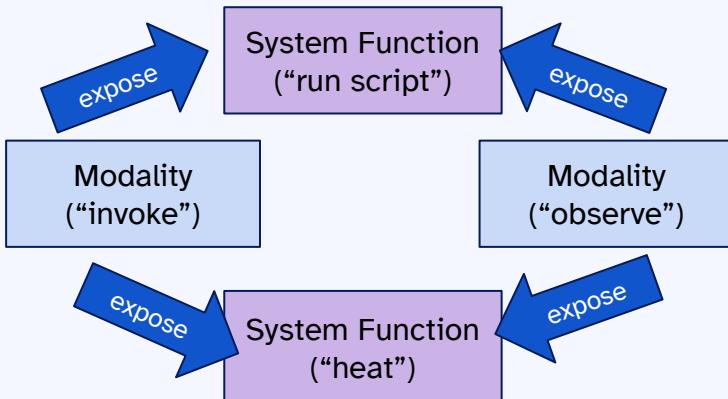
# Cross-cutting modalities



# Mapping the functional architecture

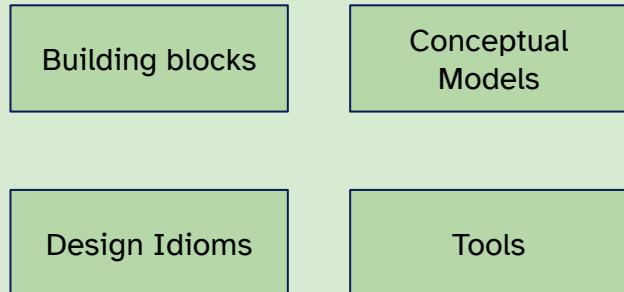
## Domain Analysis

### Functional Architecture

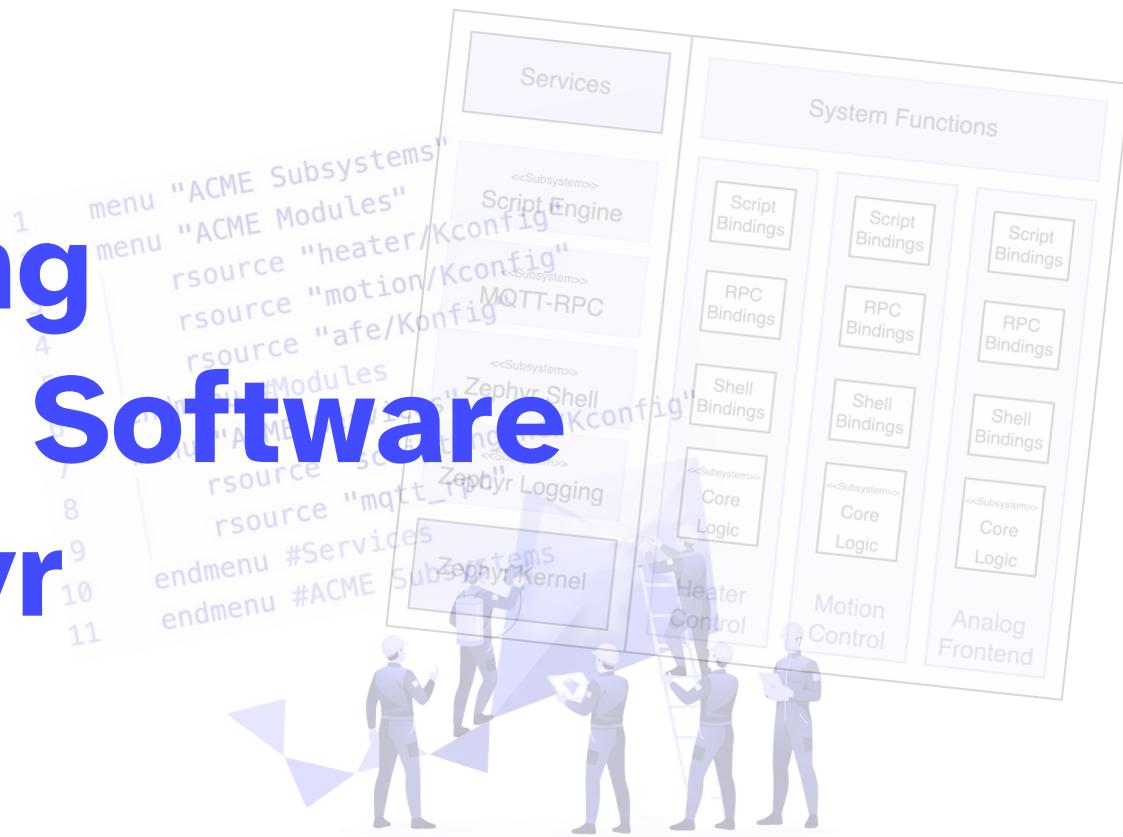


## Technical Framework

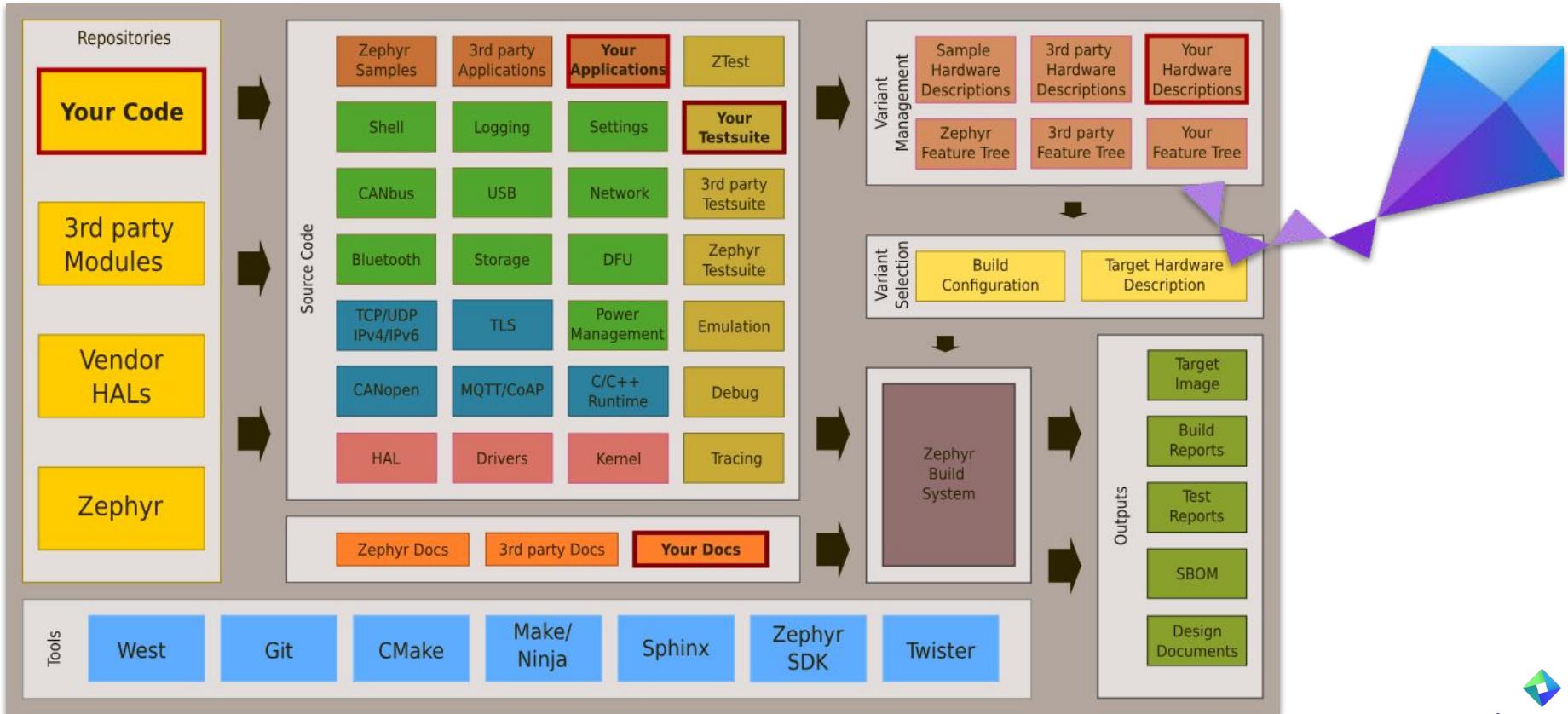
### Component Architecture



# Architecting Embedded Software with Zephyr



# Zephyr - A modern embedded Software Framework



# Zephyr's Conceptual Models



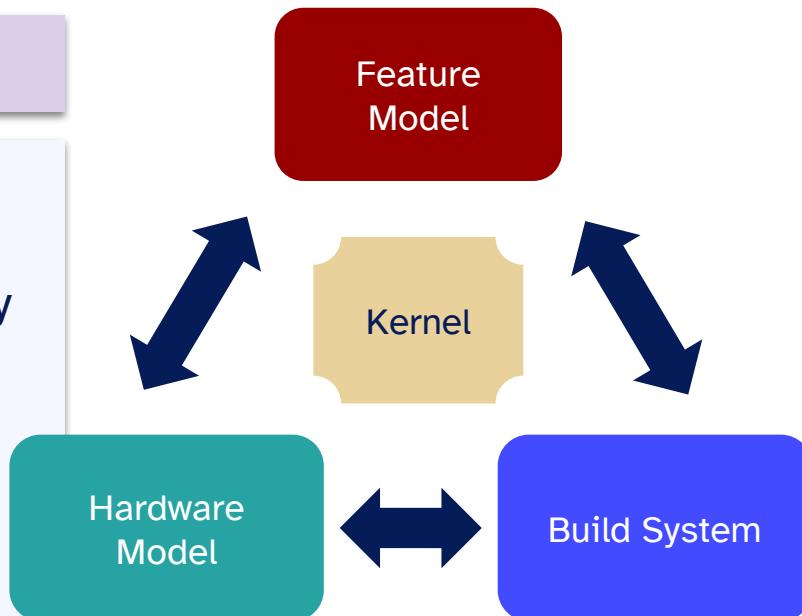
**Programming Model:** RTOS Kernel

**Plus 3 domain-specific models**

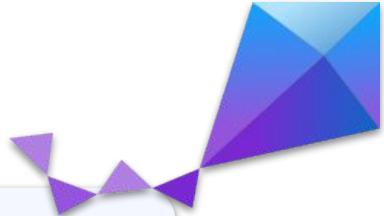
**Feature Model:** to select desired functionality

**Hardware Model:** to describe hardware properties

**Build System:** to describe build process



# Zephyr's High-Level Building Blocks



## Applications

**Subsystems** - have own runtime context via Tasks, Work Queues

**Libs** - collections of functions for synchronous invocation

**Drivers** - implement HW-specific details against common device APIs

**Kernel** - Basic RTOS primitives for synchronization, data passing

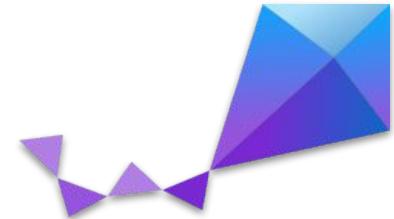
SW-Architecture needs to **create** or **re-use** these **building blocks** to **express** the **functional architecture** (functions, modalities).

# (Some of) Zephyr's Design Idioms

- **RTOS API**
  - implied by Programming model
- **CPP (C-Pre-Processor) driven Code Generation**
  - non-typed meta-programming
- **APIs from Function Pointer Structs**
  - decouples interface users from implementors
- **Iterable Sections**
  - build-time resolvable plugin mechanism

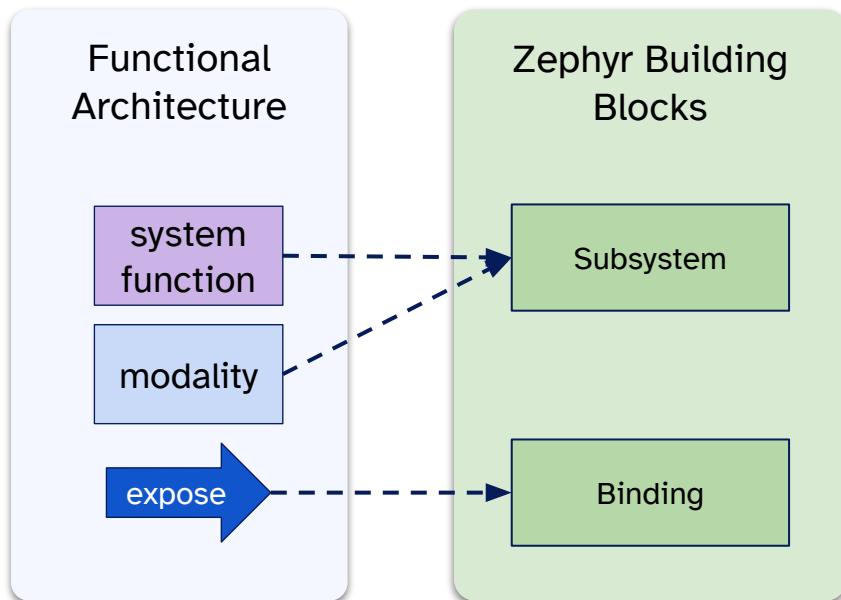


# Mapping the functional architecture



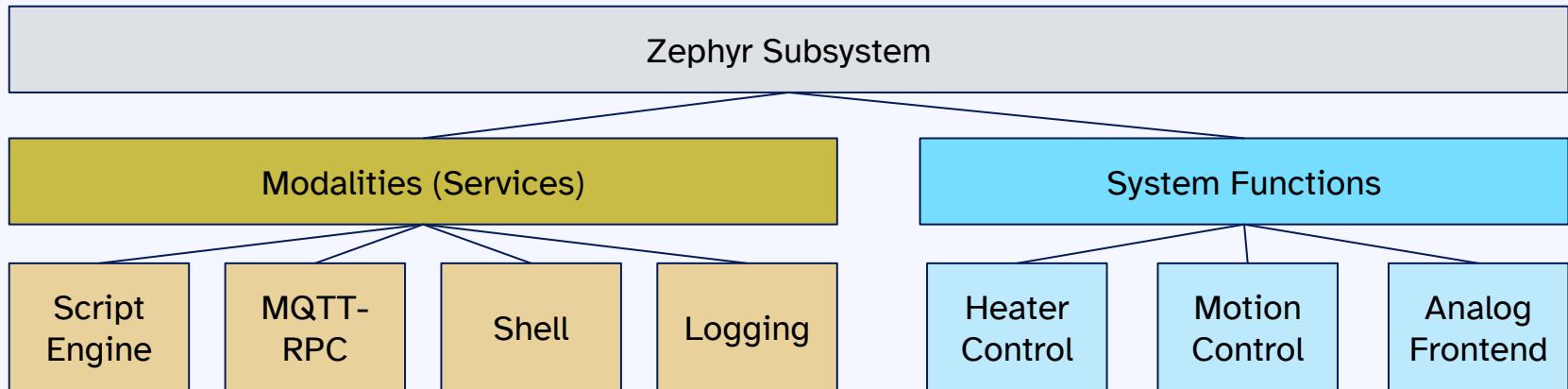
- Modalities map naturally to (existing) Zephyr subsystems
- System functions become additional subsystems
- Services expose aspects of system functions via bindings

Mapping **preserves structural relationships** of functional architecture



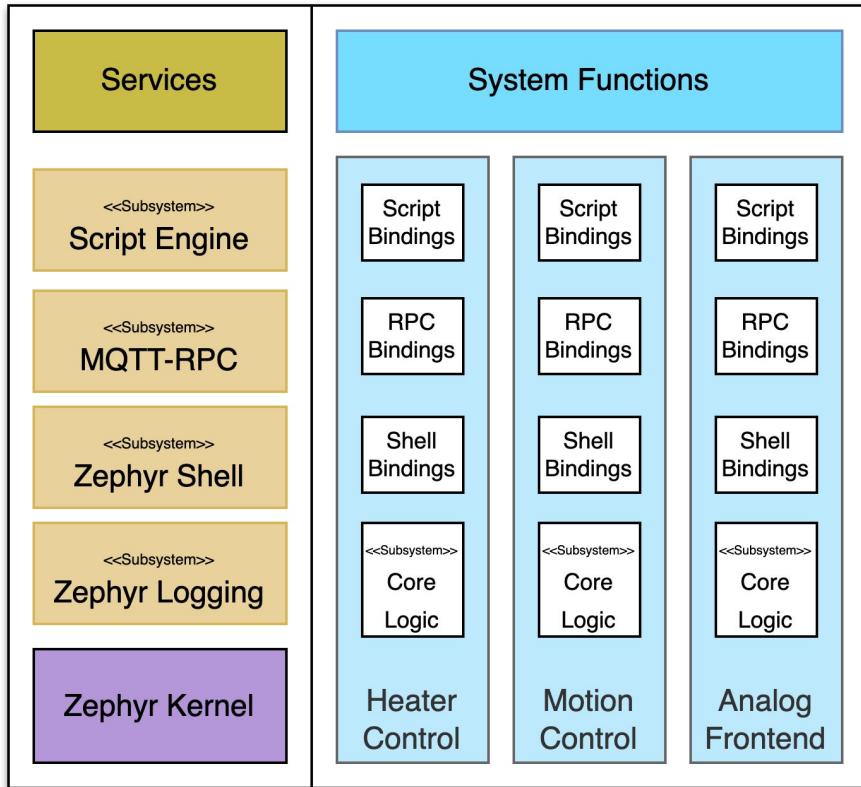
# Functional Architecture & Component Architecture

**Our Example:** Test rig for life-science experiments



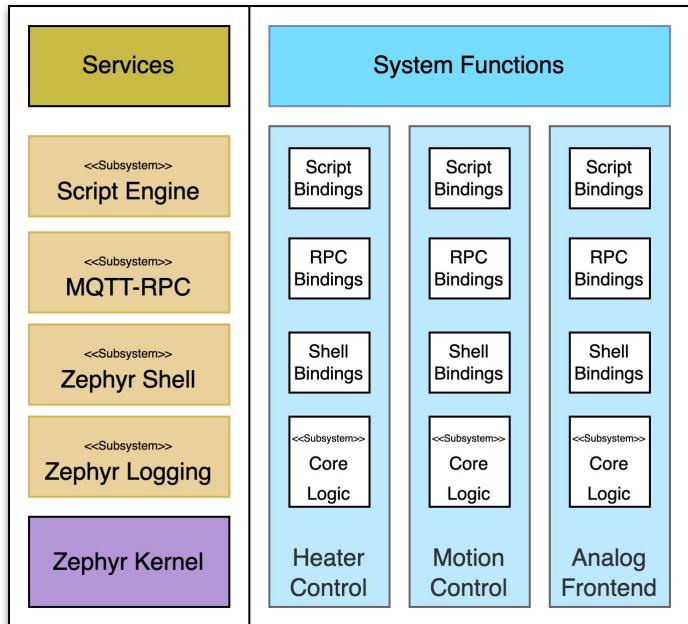
- Decomposition into System-Level Functions & System Services
- Modalities & Functions mutually independent from each other

# Functional Architecture & Component Architecture



- Zephyr provides many services already
  - Shell, Logging, Settings, ...
- Each Zephyr service also provides extension points
  - `SHELL_CMD`,
  - `LOG_MODULE_DEFINE`,
  - `SETTINGS_STATIC_HANDLER_DEFINE`
  - ...
- Use conceptual model and idioms to implement system function specific subsystems

# Modeling Software Features w/ Kconfig



```
1 menu "ACME Subsystems"
2 menu "ACME Modules"
3     rresource "heater/Kconfig"
4     rresource "motion/Kconfig"
5     rresource "afe/Konfig"
6 endmenu #Modules
7 menu "ACME Services"
8     rresource "scriptengine/Kconfig"
9     rresource "mqtt_rpc"
10 endmenu #Services
11 endmenu #ACME Subsystems
```

Functional  
Architecture



Software  
Architecture

# Modeling Software Features w/ Kconfig

Subsystems mutually independent

- enable/disable

Bindings depend on service providing corresponding extension point

Feature tree mapped to build system

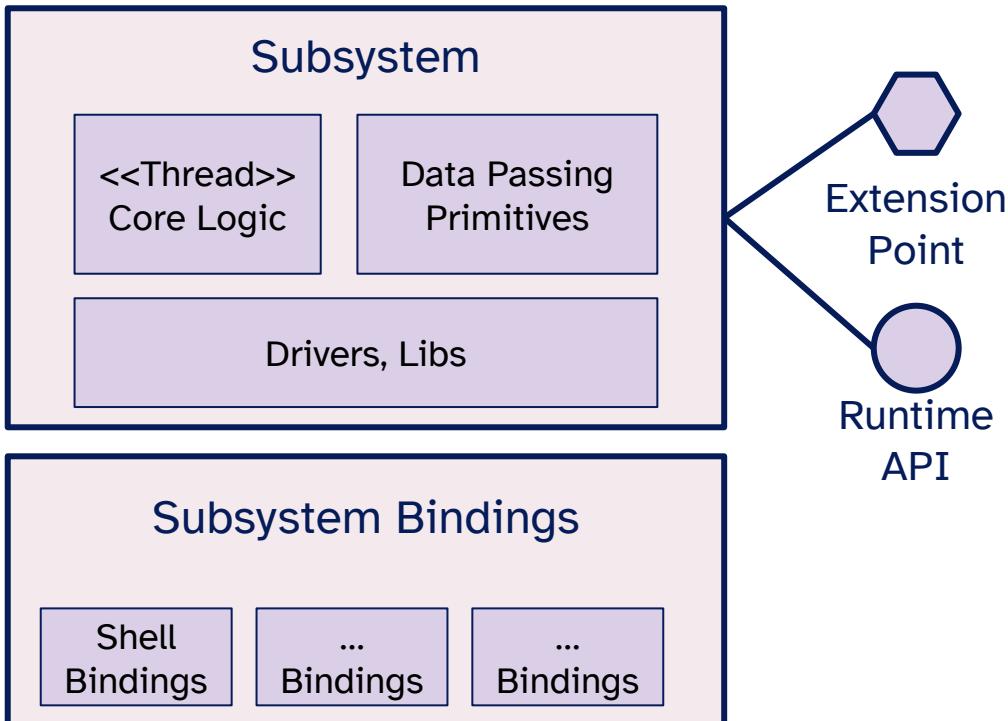
```
1  menuconfig ACME_SUBSYS_HEATER # option to toggle the entire subsystem on/off
2  2    bool "Heater subsystem"
3    help
4      The Heater subsystem is responsible for measuring and controlling
5      the temperature.
6
7  if ACME_SUBSYS_HEATER
8
9    config ACME_SUBSYS_HEATER_THREAD_STACK_SIZE
10      int "Stack size of subsystem thread"
11      default 2048
12
13    config ACME_SUBSYS_HEATER_MQTT_RPC
14      bool "Enable MQTT-RPC bindings for $(subsys-str) subsystem"
15      depends on ACME_MQTT_RPC
16
17    config ACME_SUBSYS_HEATER_SHELL
18      bool "Enable shell bindings for $(subsys-str) subsystem"
19      depends on SHELL
20
```

```
1 zephyr_library_named(acme-heater)
2
3 zephyr_library_sources(heater.c)
4 zephyr_library_sources_ifdef(CONFIG_ACME_SUBSYS_HEATER_SHELL heater_shell.c)
5 zephyr_library_sources_ifdef(CONFIG_ACME_SUBSYS_HEATER_MQTT_RPC heater_mqttrpc.c)
6 zephyr_library_sources_ifdef(CONFIG_ACME_SUBSYS_HEATER_SCOPE heater_scope.c)
7
```

# Designing Software with Zephyr



# Designing Subsystems for Zephyr



- Subsystems provide own runtime context
- Runtime API wraps Data Passing Primitives to interact with core logic
- Bindings “hook” into other subsystems
  - primary place to use the Runtime API

# Designing Subsystems for Zephyr

Extension Point

Runtime API

```
heater_shell.c
scriptengine.h
heater_script.c
scriptengine.c
```

heater\_shell.c

```
1 #include <zephyr/shell.h>
2 #include <acme/heater.h>
3
4 static int cmd_heater_on(const struct shell *sh,
5                         size_t argc, char **argv) {
6     return heater_on();
7 }
8
9 static int cmd_heater_off(const struct shell *sh,
10                         size_t argc, char **argv) {
11     return heater_off();
12 }
13
14 SHELL_STATIC_SUBCMD_SET_CREATE(sub_heater,
15     SHELL_CMD(on, NULL, "Turn on heater"),
16     SHELL_CMD(off, NULL, "Turn off heater"),
17     SHELL_SUBCMD_SET_END);
18
19 SHELL_CMD_REGISTER(heater, &sub_heater,
20                     "Heater commands, NULL");
```

scriptengine.h

```
1 #include <zephyr/sys/iterable_sections.h>
2 #include <acme/lib/lua/lua.h>
3
4 // many other things here
5
6 const struct {
7     const char *name;
8     int (*)(lua_State *L) register_func;
9 } script_function_entry;
10
11 #define SCRIPT_ENGINE_REGISTER_FUNC(_name, _register_func) \
12     static const STRUCT_SECTION_ITERABLE(script_function_entry, _name) = { \
13         .name = STRINGIFY(_name), \
14         .register_func = _register_func \
15     }
16
```

heater.h

```
1 #include <zephyr/kernel.h>
2
3 /**Public API of the Heater Subsystem */
4
5 int heater_on();
6 int heater_off();
```

heater\_script.c

```
1 #include <acme/scriptengine.h>
2 #include <acme/heater.h>
3
4 static int l_heater_on(lua_State *L){
5     int result = heater_on();
6     lua_pushinteger(L, result);
7     return 1;
8 }
9
10 SCRIPT_ENGINE_REGISTER_FUNC(heater_on, l_heater_on);
```

scriptengine.c

```
1 static int register_functions()
2 {
3     STRUCT_SECTION_FOREACH(script_function_entry, entry){
4         lua_pushfunction(scriptengine.L, entry.register_func);
5         lua_setglobal(scriptengine.L, entry.name);
6     }
7 }
```

# Applications as Configuration Management Containers

prj.conf

```
CONFIG_ACME_SERVICE_SCRIPTING=y  
CONFIG_ACME_SERVICE_MQTTRPC=y
```

```
CONFIG_ACME_SUBSYS_MOTION=y  
CONFIG_ACME_SUBSYS_HEATER=y  
CONFIG_ACME_SUBSYS_AFE=y
```

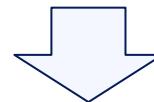
dev-overlay.conf

```
CONFIG_LOGGING=y  
CONFIG_SHELL=y
```

main.c

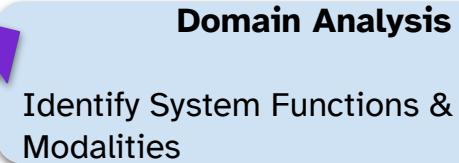
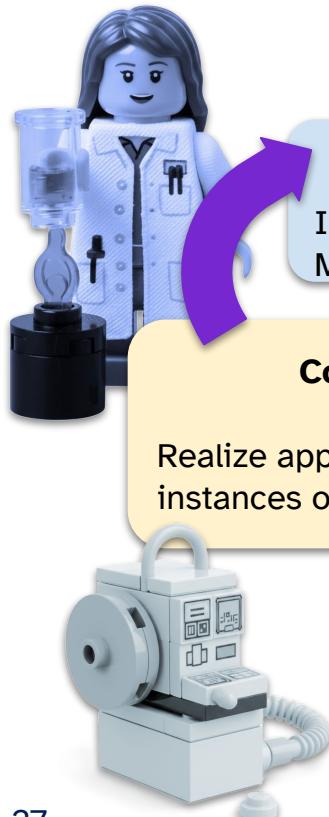
```
int main(int argc, char** argv){  
    return 0;  
}
```

- Any Zephyr application is a concrete instance of the feature model
- Relevant features described in **prj.conf**
- Configuration fragments can be merged at build-time:
  - context-of-use (**prod** vs **dev** vs **test**)
  - hardware (**board**-specific overlays)



Ideally, applications do not contain any additional code

# Summing up



## Configure Application

Realize applications as context-aware instances of the underlying feature model

## Mapping

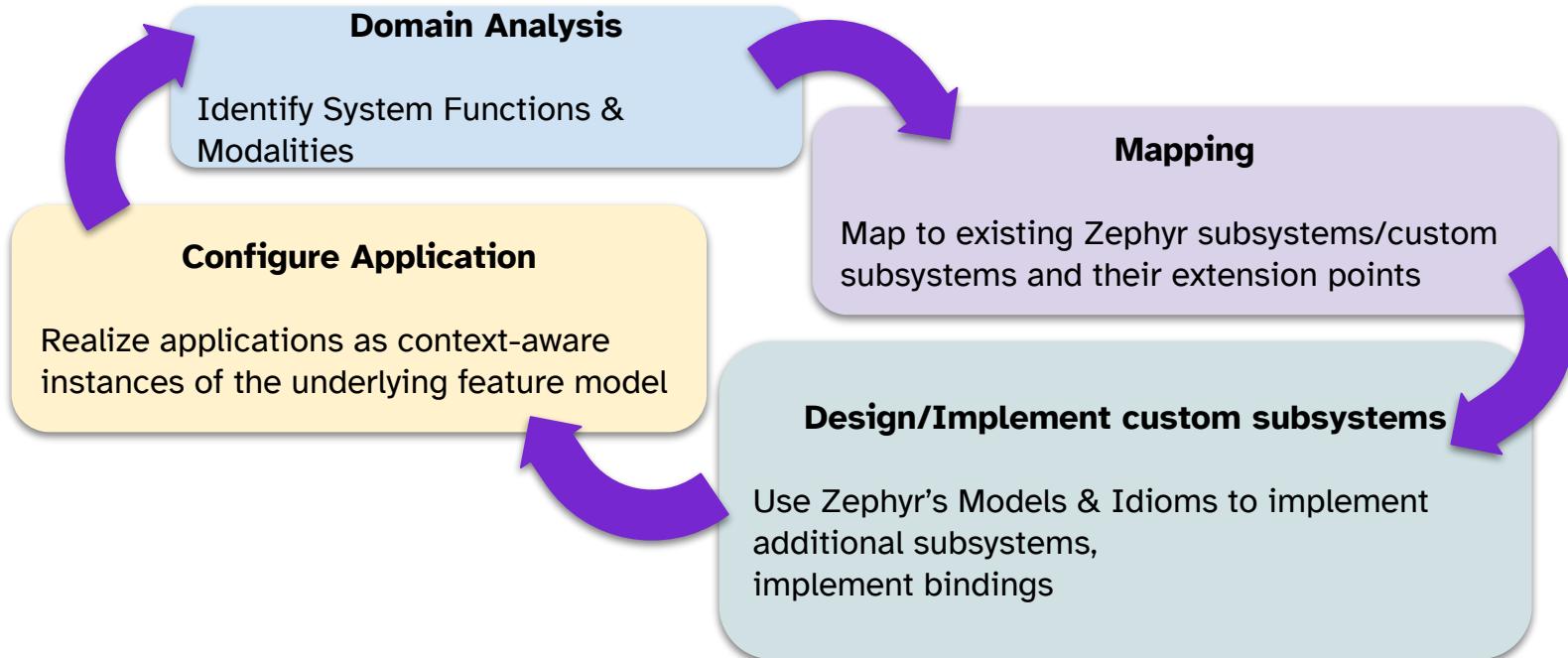
Map to existing Zephyr subsystems/custom subsystems and their extension points

## Design/Implement custom subsystems

Use Zephyr's Models & Idioms to implement additional subsystems, implement bindings

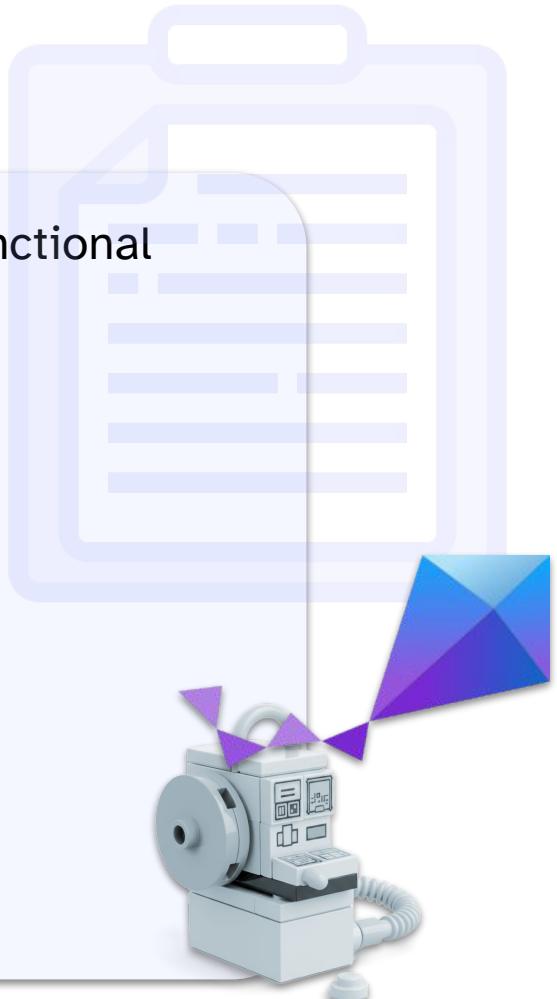
A screenshot of a code editor showing two tabs: 'C' and 'Zephyr'. The 'C' tab contains standard C code for a driver, including header includes, function prototypes, and implementations. The 'Zephyr' tab shows Zephyr-specific code using the Kconfig and Device Tree (DT) models, including 'menuconfig' definitions and 'DT' entries for components like 'leds' and 'uart'. The code is annotated with comments explaining the Zephyr-specific constructs.

# Summing up



# Conclusions

- Starting an embedded systems design from its functional decomposition bears many benefits
  - clearly analysed (functional) dependencies
  - consistent, domain-oriented terminology
- Zephyr supports the work of SW architects with
  - advanced models and design idioms
  - a rich set of existing functionalities
- When designing with Zephyr always consider
  - feature model and build system integration
  - re-using existing subsystems



# Thank You



Check out our Zephyr Hands-On Trainings

Find out more

<https://www.inovex.de/de/training/zephyr-basic-training/>



**Dr. Tobias Kästner**  
**Solution Architect Medical IoT**

[tobias.kaestner@inovex.de](mailto:tobias.kaestner@inovex.de)

+49 152 3314 8940

Allee am Röthelheimpark 11,  
91052 Erlangen



Tobias Kaestner



@tobiaskaestner



@tobiaskaestner